Real Time Vehicle Monitoring

GPS-GSM/GPRS Vehicle Modules

Fuel level Sensors and Adapters

Office PC Based Monitoring System

WEB Based Monitoring System







About Real Time Monitoring System

About Real Time Monitoring

- Operative monitor vehicle real location, vehicle movement and movement parameters;
- Operative monitor vehicle status and parameters of external sensor;
- Monitor fuel consumption, fueling and fuel drain;
- Monitor driver activity, driver behaviour (eco-driving) and quality of driving;
- Collect information about vehicle movement, driving style, driver activity, fuel consumption, information from external sensors and store it in data base for posterior analyzing.

* – real time monitoring system is based on satellite system of geographical coordinates definition (GPS System) and GSM/GPRS data communication.

* – outside GSM/GPRS coverage, or "GSM network busy" all data stored in modules internal memory for automatic posterior data transmitting.



About Fuel Monitoring



In general "Real Time" fuel monitoring system consist of next main components:

• Fuel level sensor with digital communication interface (GuardMagic DLLS1 series). Fuel level sensor make measurement of fuel level in fuel tank and send this data to vehicle GPS-GPRS module . (System support up to THREE regular fuel tanks and up to ELEVEN cargo or service fuel tanks);

• Vehicle GPS-GPRS module (GuartdMagic VF2 or GuardMagic VB6, VB7, VB8) collect information from fuel sensor and send collected information to monitoring station;

• Monitoring station, - collect the fuel data and other information from vehicle modules, store this information in "Data Base", make analyzing of received information and generate the series of reports and diagrams.



Monitoring Structure in General



- In vehicle locate GPS-GSM/GPRS module (GuardMagic VF or GuardMagic VB series) that in full automatic mode collect and send to monitoring station information about vehicle location and parameters of vehicle movement, vehicle status, information from external sensors etc.;
- Communication channel (GSM/GPRS+ Internet) for the sending information from vehicle module to "Monitoring Station";
- "Monitoring Station" receive information from all vehicle, store this information in data base, processing information and generate reports and graph about vehicle activity and vehicle status.



System Allow

GuardMagic "Real Time" vehicle and fuel monitoring system allows:

- company owners, directors, transport managers always have a real information of vehicles and vehicle fleet, vehicle trip, vehicle utilization, vehicle driving parameters, fuel usage;
- watch in real time vehicle location and traffic parameters;
- increase vehicle or special machinery effectiveness;
- minimize non-productive expenses;
- supervise vehicle trip and parameters of movement;
- supervise fuel usage;
- prevent (or minimize) fuel theft;
- supervise vehicle operation time;
- prevent not authorized use of transport;
- supervise drivers working hours and/or operators working hours effectiveness;
- compare vehicle utilization, driving safety and driver behaviour.



Monitoring All types of Vehicle and Machinery



Cars, Pickup, SUV GuardMagic VF2, VB6 GuardMagic DAFS1



Passenger Buses GuardMagic VF2, VB6 GuardMagic DLLS1



Mining Truck, Mining Machinery GuardMagic VF2, VB6, VB7 GuardMagic DLLS1



LCV GuardMagic VF2, VB6 GuardMagic DAFS1



Refrigerator Trucks GuardMagic VB7 GuardMagic DTS GuardMagic DLLS1



Building Machinery GuardMagic VF2, VB6 GuardMagic DLLS1

7



Minibuses GuardMagic VF2, VB6 GuardMagic DAFS1



Road Fuel Tanker GuardMagic VB8 GuardMagic DLLE1ct + JBB01



Road Building Machinery GuardMagic VF2, VB6 GuardMagic DLLS1



Trucks GuardMagic VF2, VB6 GuardMagic DLLS1



Utility and Special Machinery GuardMagic VF2, VB6, VB7 GuardMagic DLLS1



Agricultural Machinery GuardMagic VF2, VB6 GuardMagic DLLS1

... and much, much more



GuardMagic System Advantages in General

- Monitor all type of vehicle (starting of car and up to road fuel tankers);
- Monitor: vehicle, vehicle driving, fuel, trailers, drivers, sensors;
- Worldwide cover operation;
- Remote monitor by GSM/GPRS network;
- Outside GSM/GPRS network modules stores all information in its memory;
- Real time vehicle location monitoring and parameters of movement;
- Driving safety monitoring and driver behavior monitoring;
- Multi tanks monitoring, up to total 14 fuel tanks for one vehicle ;
- Real time monitor fuel level in all fuel tanks: regular and cargo;
- Temperature monitoring;
- External sensors monitoring;
- Generate the lots of reports and graphs for vehicle, fleet, drivers, trailers;
- Universal data communication protocol for all modules;
- System functionality growing





GuardMagic GPS-GSM/GPRS Vehicle Modules

GuardMagic GPS-GSM/GPRS Vehicle Modules

GuardMagic VF2

Universal compact vehicle GPS/ GSM-GPRS module with fuel monitoring function (multi tanks supports) and acceleration/ deceleration monitoring.

GuardMagic VB6, VB6lite

Universal vehicle GPS/ GSM-GPRS module with fuel monitoring function (multi tanks supports), acceleration/ deceleration monitoring and driver identification function.

GuardMagic VB7, VB7lite

Advanced vehicle GPS/ GSM-GPRS module with fuel monitoring function (multi tanks supports), temperature monitoring, acceleration/ deceleration monitoring and driver identification function. Module has TWO digital fuel bus (EIA-485).

GuardMagic VB8

Special GPS/ GSM-GPRS module dedicated to use in road fuel tankers. Module allow to monitor fuel level up to 11 cargo fuel compartments and monitor fuel quality in SIX compartments. Module has: driver identification function, TWO digital fuel bus

(EIA-485).











Advantages Of GuardMagic Vehicle Modules

- installation on any type of transport (truck, lorry, car, road tanker, combine, tractor, bulldozer, building and special machinery etc.);
- connection to external logical sensors;
- in full automatic mode collect and transmit to monitoring station information about vehicle location, parameters of vehicle moving, active driver, driving style, status and information from of external sensors;
- outside GSM coverage store all information in internal non-volatile memory and posterior in full automatic transmit stored information to monitoring station;
- Internal memory for about 110 Thousands record;
- multi tanks support functionality (independently monitor many fuel tanks);
- high fuel resolution: 1024 or 4096 levels;
- digital communication interface with fuel level sensors (very high noise protection);
- monitor fuel temperature in fuel tanks;
- driver identification function;
- monitor driver behaviour (eco-driving) and quality of driving;
- Immobilization function (based on driver ID);
- remote engine start blocking (engine blocking) functionality;
- several operation mode: transport, special machinery, active stand by, sleep;
- protection of power circuit and signal against an over voltage and over polarity;
- and much more...

GuardMagic vehicle and fuel monitoring

About GuardMagic VF2 Module



GuardMagic VF2: universal compact vehicle GPS/ GSM-GPRS module with fuel monitoring function (multi tanks supports) and acceleration/deceleration monitoring. GuardMagic VF2 module designed for remote supervision of mobile object movement (vehicle, special machinery, etc.) and remote fuel monitoring.

Module supports up to THREE regular fuel tanks.

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Module has internal memory for 110Thousand records (if GSM signal is absent).

GuardMagic VF2 benefit:

- adaptive data fixing;

-transmit vehicle movement parameters: speed, acceleration, deceleration;

- safety and eco-driving support;
- multi tanks support functionality;
- support up to THREE fuel level sensors with digital communication interface (THREE regular fuel tanks)
- or support ONE analog fuel level sensor (ONE regular fuel tank);
- digital industrial communication interface with fuel level sensors (EIA-485);
- collect information from fuel level sensors: fuel level and temperature;
- high resolution in fuel bus (1024 or 4096 levels);
- fuel bus status diagnostic;
- internal non-volatile memory for the about 110 thousands of records;
- programmed active stand-by mode.

GuardMagic VF2 Main Functionality

Main:

- Coordinates definition (GPS position) and parameters of vehicle movement;

- Transmitting by GSM/GPRS network to the Monitoring Station coordinates of truck, parameters of movement, fuel level in truck fuel tanks, engine On-Off status, panic button pressing;

- Storing the GPS data and data from external sensor and circuits in internal non-volatile memory and posterior transmitting this information by GSM/GPRS to monitoring station;

- Automatic storing data in internal memory than GPRS connection is absent;

-Automatic starting sending data from memory than GPRS connection appear;

-Two types of mode:

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operation mode;programming mode.

- Two types of working in operation mode:
 - transport mode;
 - special machinery mode;
- Three type of operation;
 - "operation";
 - -" active stand by";
 - "sleeping"
- Programming the periodicity of data fixing;
- User programming module configuration;
- Remote engine starting blocking;
- Remote module reprogramming.

Others:

Transition in "active stand by" mode and "sleep mode" after deenergizing Ignition;
Automatic activation from "active stand by" mode or "sleep mode" in case of at activation of any logical inputs;

- Protection of power circuit and signal against an over voltage;

- Satellite time synchronization;

GuardMagic VF2 Connection and Operation



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About GuardMagic VB6, VB6lite Modules



GuardMagic VB6: universal vehicle GPS/ GSM-GPRS module with fuel monitoring function (multi tanks support), acceleration/ deceleration monitoring and driver identification function.

GuardMagic VB6 module designed for remote supervision of mobile object movement (vehicle, special machinery, etc.), vehicle status monitoring, fuel in regular tanks monitoring and active driver monitoring.

Module supports up to THREE regular fuel tanks.

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Module has internal memory for 110Thousand records (if GSM signal is absent).

GuardMagic VB6 benefit:

- adaptive data fixing;

-transmit vehicle movement parameters: speed, acceleration, deceleration;

- safety and eco-driving support;
- multi tanks support functionality;
- support up to THREE fuel level sensors with digital communication interface (THREE regular fuel tanks)
- driver identification;

- digital industrial communication interface with all fuel level sensors (EIA-485);

- collect information from fuel level sensors: fuel level and temperature;
- -high resolution in fuel bus (1024 or 4096 levels);-external sensors monitoring;
- fuel bus status diagnostic;
- internal non-volatile memory for the about 110 thousands of records;
- programmed active stand-by mode.

GuardMagic VB6 Main Functionality

Main:

Coordinates definition (GPS position) and parameters of vehicle movement;
Transmitting by GSM/GPRS network to the Monitoring Station coordinates of truck, parameters of movement, fuel level in regular fuel tanks, engine On-Off status, panic button pressing, event button pressing, engine RPM, engine overheat, status of alarm system;
Storing the GPS data and data from external sensor and circuits in internal non-volatile memory and posterior transmitting this information by GSM/GPRS to monitoring station;

- Automatic storing data in internal memory than GPRS connection is absent;

-Automatic starting sending data from memory than GPRS connection appear;

-Driver identification;

-Guard function;

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-Immobilization function (by driver ID);

-Two types of mode:

- operation mode, programming mode.
- Two types of working in operation mode:
 - transport mode, special machinery mode;
- Three type of operation;
 - "operation", " active stand by", "sleeping";
- Programming the periodicity of data fixing;
- Programming the module configuration;
- Remote engine starting blocking;
- Remote On/Off customer relay;
- Remote module reprogramming.

Others:

- Transition in "active stand by" mode and "sleep mode" after deenergizing Ignition;
 Automatic activation from "active stand by" mode or "sleep mode" in case of at activation of any logical inputs;
- Protection of power circuit and signal against an over voltage;
- Satellite time synchronization;

GuardMagic VB6 Module Connection

Main circuits connection:

- Main power supply;
- External reserve battery;
- -- GPS antenna-receiver (from complete set);
- Ignition circuit;
- -Up to THREE fuel level sensor in truck regular fuel tanks (EIA-485);
- -Driver identification reader;
- -Truck alarm system;
- -"PANIC" button;
- "Event" button;
- Vehicle Engine RPM sensor (circuit),
- Crash sensor, fuel tank empty sensor, engine overheat sensor;
- External buzzer;
- Engine start blocking relay;
- Customer relay.

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About GuardMagic VB7, VB7lite Modules



GuardMagic VB7: universal vehicle GPS/ GSM-GPRS module with fuel and temperature monitoring function, acceleration/ deceleration monitoring and driver identification function

GuardMagic VB7 module designed for remote supervision of mobile object movement (vehicle, special machinery, etc.), vehicle status monitoring, fuel in regular and service tanks monitoring and active driver monitoring. Module supports up to THREE regular fuel tanks and up to FOUR service (cargo) tanks; Module has internal memory for 110Thousand records (if GSM signal is absent).

GuardMagic VB7 benefit:

- adaptive data fixing;
- transmit vehicle movement parameters: speed, acceleration, deceleration;
- safety and eco-driving support;
- -multi tanks support functionality(THREE in regular fuel tanks and FOUR sensors in service tanks);
- support up to SEVEN temperature sensors;
- driver identification;
- two digital communication interface EIA-485 for communication with fuel level sensors;
- collect information from fuel level sensors: fuel level and temperature;
- -high resolution in fuel bus (1024 or 4096 levels);-external sensors monitoring;
- fuel bus status diagnostic;
- internal non-volatile memory for the about 110 thousands of records;
- programmed active stand-by mode.





GuardMagic VB7 Main Functionality

Main:

- Coordinates definition (GPS position) and parameters of vehicle movement;

- Transmitting by GSM/GPRS network to the Monitoring Station coordinates of truck, parameters of movement, fuel level in regular and service fuel tanks, temperature information from temperature sensors, engine On-Off status, panic and event buttons pressing, engine RPM, engine overheat, status

of alarm system;

-Storing the GPS data and data from external sensor and circuits in internal non-volatile memory than GPRS connection is absent and posterior transmitting this information to monitoring station ;

-Automatic starting sending data from memory than GPRS connection appear;

-Driver identification;

-Guard function;

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-Immobilization function (by driver ID);

-Two types of mode:

- operation mode, programming mode.
- Two types of working in operation mode:
 - transport mode, special machinery mode;
- Three type of operation;
 - "operation", " active stand by", "sleeping";
- Programming the periodicity of data fixing;
- Programming the module configuration;
- Remote engine starting blocking;
- Remote On/Off customer relay;
- Remote module reprogramming.

Others:

- Transition in "active stand by" mode and "sleep mode" after deenergizing Ignition;

- Automatic activation from "active stand by" mode or "sleep mode" in case of at activation of any logical inputs;

- Protection of power circuit and signal against an over voltage;

- Satellite time synchronization;

GuardMagic VB7 Module Connection

Main circuits connection:

- Main power supply;
- External reserve battery;
- -- GPS antenna-receiver (complete set);
- Ignition circuit;
- -Up to THREE fuel level sensor in truck regular fuel tanks (EIA-485);
- -Up to FOUR fuel level sensor in service fuel tanks (EIA-485);
- -Up to SEVEN temperature sensors by 1wire interface;
- -Driver identification reader;
- -Truck alarm system;
- -"PANIC" and ""Event" buttons;
- Engine RPM sensor, crash sensor, fuel tank empty sensor, engine overheat sensor;
- External buzzer;
- Engine start blocking relay;
- Customer relay.

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About GuardMagic VB8 Module



GuardMagic VB8: special compact tanker-truck GPS/ GSM-GPRS module dedicated to use on tanker-truck application.

GuardMagic VB8 module designed for remote supervision of road fuel tankers and its fuel compartments.

GuardMagic VB8 module monitor: tanker movement and tanker status, fuel in cargo tanks and regular truck tanks, fuel quality in cargo tanks, driving safety, active driver, active trailer. Module supports up to THREE truck regular fuel tanks and up to ELEVEN cargo compartments ; Module has internal memory for 110Thousand records for storing data (if GSM signal is absent).

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GuardMagic VB8 benefit:

- multi tanks support functionality;
- independently monitor fuel level up to 11 fuel cargo compartments and up to 3 truck fuel tanks;
 - independently monitor fuel quality (density/ viscosity) in up to SIX fuel cargo compartments;
 - two digital communication interface EIA-485 with fuel level sensors and fuel quality sensor;
 -high resolution in fuel bus (1024 or 4096 levels);
 -support up to SEVEN temperature sensors;
- driver identification;
- trailer identification;
- adaptive data fixing;
- transmit vehicle movement parameters: speed, acceleration, deceleration;
- safety and eco-driving support;
- synthetic ignition;
- fuel bus status diagnostic;
- internal non-volatile memory for the about 110 thousands of records;
- programmed active stand-by mode.

GuardMagic VB8 Main Functionality

Main:

- Coordinates definition (GPS position) and parameters of vehicle movement; - Transmitting by GSM/GPRS network to the "Monitoring Station" coordinates of fuel tanker, parameters of movement, fuel level in cargo compartments and truck regular fuel tanks, fuel quality in cargo compartments, temperature information from temperature sensors, engine On-Off status, panic and event buttons pressing, engine RPM, engine overheat, status of alarm system; -Storing the GPS data and data from external sensors and circuits in internal non-volatile memory than GPRS connection is absent and posterior transmitting this information to monitoring station; -Automatic starting sending data from memory than GPRS connection appear;

-Driver identification and trailer identification; -Guard function;

-Immobilization function (by driver ID);

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- -Two types of mode:
 - operation mode, programming mode.
- Two types of working in operation mode;
- Three type of operation;
 - "operation", " active stand by", "sleeping";
- Programming the periodicity of data fixing;
- Programming the module configuration;
- Remote engine starting blocking;
- Remote On/Off customer relay;
- Remote module reprogramming.

Others:

two steps over speed sound notification;
Transition in "active stand by" mode and
"sleep mode" after deenergizing Ignition;
Automatic activation from "active stand by" mode or "sleep mode" in case of at activation of any logical inputs;

- Protection of power circuit and signal against an over voltage;

- Satellite time synchronization;

GuardMagic VB8 Module Connection

Main circuits connection:

-Up to ELEVEN fuel level sensor in cargo fuel tank compartments (EIA-485);

-Up to THREE fuel level sensor in truck regular fuel tanks (EIA-485);

- Up to SIX fuel quality sensors (EIA-485);

- Up to SEVEN temperature sensors by 1-wire interface;

- -Driver identification reader;
- -Trailer identification module;
- Truck alarm system;
- Main power supply;
- External reserve battery;
- Ignition circuit;

--GPS antenna-receiver (from complete set);

- -"PANIC" and ""Event" buttons;
- Engine RPM sensor, crash sensor, fuel tank empty sensor, engine overheat sensor;
- External buzzer;
- -Engine start blocking relay;
- Customer relay.

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Driver Identification by i-Button

for modules GuardMagic VB6, Guardmagic VB7, GuardMagic VB8

The iButton[®] (by Maxim/Dallas Semiconductor) device is a computer chip enclosed in a robust stainless steel can.

Each iButton[®] device has a unique and unalterable code laser etched onto its chip inside the can. This code used as a key or identifier for each iButton device.

The silicon chip within the iButton device is protected by the ultimate durable material: stainless steel. You can drop an iButton device, step on it, or scratch it.

The iButton device is wear-tested for 10-year durability.

i-Buton

Driver has its own iButton[®] and iButton code is the ID code of driver in monitoring system.

By simply touching iButton[®] device to iButton Reader (Touch Pad) GuardMagic VB module read this code (driver ID code) and send this code to monitoring station.

Using ID driver code allow to add additional immobilization function in the vehicle: only reading the correct ID code (authorized driver) allow to start the vehicle engine.



i-Buton Reader (Touch Pad)





GuardMagic Fuel Level Sensors and Sensor Adapters

GuardMagic Fuel Sensor Related Products

GuardMagic DAFS1: adapter for resistive type floating fuel level sensor with EIA-485 communication interface. GuardMagic DAFS allow by very economical way embed fuel monitoring function for cars, SUV, VANs, LCV in vehicle monitoring system.

GuardMagic DLLS1 series: robust digital fuel level sensor (for operation in vehicle regular fuel tanks). -available sensor length: from 0,3m and up to 2,5m; -multi tanks support functionality -digital communication interface EIA-485; -Internal data processing; -robust construction.

GuardMagic DLLE1ct series: robust digital fuel level sensor for operation in hazardous area (for road fuel tanker cargo tanks). -available sensor length: from 1,3m and up to 2,5m;

- -multi tanks support functionality
- -digital communication interface EIA-485;
- -Internal data processing;
- -robust construction.

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In Brief About PC Monitoring Software/Service Functionality

About Monitoring Software and Monitoring Service



All World Coverage and All World Operation



About Monitoring Software and Monitoring Service (VehicleStation, FleetStation: "Main Operation" Window)



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About Monitoring Software and Monitoring Service (VehicleStation, FleetStation: "Main Operation" Window)



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About Monitoring Software and Monitoring Service (VehicleStation, FleetStation: "Chart" Window)



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About Monitoring Software and Monitoring Service (PowerTrace Service: "Main Operation" Window)



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Detailed Starting Condition Report

Vehicle Name: Plate Number:	Toyota Hilux BAM6076	(Nodel Group	e -		
Time Period:	17 сен 2014 00:00) – 17 сен 201	4 23:	59		
Date Time	Start Type	First Name		Sumame	Pers ID	
17-09-2014 0.09:26	correct driver	Ker	пу	Ken	010256-11111	
17-09-2014 1:33:18	without identification	110 111				
17-09-2014 3:38:48	correct driver	Kenny		Ken	010256-1111	
17-09-2014 4:33:19	correct driver	Ker	ny	Ken	010256-11111	
17-09-2014 5:23:25	without identification					
17-09-2014 5:54:06	correct driver	Ker	ny	Ken	010256-11111	
17-09-2014 6:03:50	without identification	111-12-14				
17-09-2014 6:11:53	correct driver	Ker	ny	Ken	010256-11111	
17-09-2014 6:39:03	without identification		1			

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Vehicle Active Driver Report

Vehicle Name:	Toyota Hilux		Model:			
Plate Number:	BAM6076		Group:			
Time Period:	17 сен 2014 00:0	ен 2014 00:00 – 17 сен 2014 23:59				
Date Time	iButton code	Name	Pers ID			
17-09-2014 0:09:26	000014FD1E81	Kenny Ker	1			
17-09-2014 1:33:18	n/a					
17-09-2014 3:38:48	000014FD1E81	Kenny Ker	1			
17-09-2014 4:33:19	000014FD1E81	Kenny Ker	1			
17-09-2014 5:23:25	n/a	h.)				
17-09-2014 5:54:06	000014FD1E81	Kenny Ker	1			
17-09-2014 6:03:50	n/a	6.1				
17-09-2014 6:11:53	000014FD1E81	Kenny Ker	1			

General Events Report

Vehicle Name:	Toyota Hilux	Model:	
Plate Number:	BAM6076	Group:	
Time Period:	17 cew 2014 00:00 - 1	7 сен 2014 23:59	

Operating Period (Calendar Days): 0 Operating Days per Period: 1 Distance: 231.022 km Summary Working Time (hh:mm:ss): 23.59.54 Summary Effective Time (hh:mm:ss): 4.13.03

Date	Event Button	L1	L2	13	Overheat	Wrong Start	No Authorization
17-09-2014	0	0	0	0	0	0	8

	(Gene	ral						I	Jtiliza	ation			
Vehicle Name: Plate Number: Time Period: OPERATION Operating Period (C Operating Days (Wc	Plate Number: KM1024 Group: Time Period: 2010-01-11 00:00:00 - 2010-01-18 00:00:00 OPERATION Operating Period (Calendar Days): 7 Operating Days (Working Days): 5						Operating Days Distance: 599.3 Summary Work							
DISTANCE Trip Distance: 348.9	939 km													
TIME Summary Working	Time (hh:mm:ss): 128:31	1:36						Using of Working Time				-	Idle Time	Parking Qty
Summary Effective	Time (hh:mm:ss): 19:12: ime (hh:mm:ss): 9:19:54	:35					12/01/2010	10.93%	2.17%	2:37:25	0:31:12	0:18:37	0:08:01	
Summary Idle Time	(hh:mm:ss): 7:48:53 me (hh:mm:ss): 9:52:41						13/01/2010	49.83%	15.77%	11:57:34	3:47:03	2:04:33	2:38:07	
PRODUCTIVITY							14/01/2010 15/01/2010	44.68%	19.73% 9.47%	10:43:23 3:43:52	4:44:05 2:16:25	0:31:47	2:45:05	
Using the Working T Effectiveness per per							15/01/2010	49.34%	9.47%	11:50:29	3:59:40	1:39:46	1:15:52	
EVENTS Event Button Presse							17/01/2010	49.34%	16.04%	13:0:54	3:59:40	2:31:43 2:13:28	0:21:41	
L1 activation (qty): 0 L2 activation (qty): 0	D						18/01/2010	48.63%	25.13%	11:40:16	6:01:54	4:14:13	0:21:41	
L3 activation (qty): 0	5						19/01/2010	48.78%	20.18%	11:42:24	4:50:38	3:24:59	13:52:13	
NOT REGULAR SI Engine Overheat (qt	ty): 0						20/01/2010	48.78%	8.82%	2:44:40	2:07:04	1:08:36	0:09:39	
Attempt To Start Wi Attempt To Start Wi	ithout Authorization (qty):	: 0					2010112010			5 h		·· · · · · · · · · · · · · · · · · · ·		
Attempt To Start Wi Attempt To Start Wi erating Period (Calendar Days erating Days per Period: 21	ithout Authorization (qty):	: 0	dated				OPERATIO	DN	F	uel U	sage)		
Attempt To Start Wi erating Period (Calendar Days erating Days per Period: 21 itance: 599.308 km mmary Working Time (hh:mm	(ithout Authorization (qty): COI s): 31 ::ss): 80:00:57	: 0	dated				OPERATIO	DN Period (Calendar Da Days (Working Days	iys): 1	uel U	sage	;		
Attempt To Start Wi erating Period (Calendar Days erating Days per Period: 21 tance: 599.308 km	(ithout Authorization (qty): COI s): 31 ::ss): 80:00:57	: 0	dated				OPERATIO Operating Operating DISTANCE	Period (Calendar Da Days (Working Days E	iys): 1	uel U	sage	;		
Attempt To Start Wi erating Period (Calendar Days erating Days per Period: 21 tance: 599.308 km nmary Working Time (hh:mm nmary Effective Time (hh:mm	(thout Authorization (qty): COI (s): 31 (:ss): 80:00:57 (:ss): 32:12:11	nsolic					OPERATIO Operating Operating DISTANCE Trip Distan	Period (Calendar Da Days (Working Days E nce: 0.447 km	iys): 1					
Attempt To Start Wi erating Period (Calendar Days erating Days per Period: 21 tance: 599.308 km mmary Working Time (hh:mm nmary Effective Time (hh:mm Date Work Starting	(thout Authorization (qty): (s): 31 (:ss): 80:00:57 (:ss): 32:12:11 Work Finishing	NSOLIC Work Time	Distance (km)	Effective Time	Driving Time	Stand Time	OPERATIO Operating Operating DISTANCE Trip Distan FUEL TAN	Period (Calendar Da Days (Working Days E Icce: 0.447 km	iys): 1	E	UEL TANK 3			
Attempt To Start Wi erating Period (Calendar Days erating Days per Period: 21 tance: 599.308 km mmary Working Time (hh:mm mmary Effective Time (hh:mm Date Work Starting 12/01/2010 12/01/2010 9:02:07	(thout Authorization (qty): (s): 31 (ss): 80:00:57 (ss): 32:12:11 Work Finishing 7 12/01/2010 11:39:32	Work Time 2:37:25	Distance (km) 4.067	Effective Time 0:31:12	0:18:37	0:12:35	OPERATIO Operating DISTANCE Trip Distan FUEL TAN Initial volum Final volum	Period (Calendar Da Days (Working Days E Ince: 0.447 km IK 1 me: 0.0 litres ne: 0.0 litres	iys): 1	<u>Fi</u> In Fi	UEL TANK 3 itial volume: (0.0 litres).0 litres		
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Attempt To Start Wi erating Period (Calendar Days erating Days per Period: 21 stance: 599.308 km mmary Working Time (hh:mm mmary Effective Time (hh:mm Date Work Starting 12/01/2010 12/01/2010 9:02:07	Ithout Authorization (qty): COI s): 31 :ss): 80:00:57 r:ss): 32:12:11 Vork Finishing 7 12/01/2010 11:39:32 6 13/01/2010 17:35:30 8 14/01/2010 15:37:21 0 15/01/2010 9:31:22 7 16/01/2010 16:50:06	Work Time 2:37:25 11:57:34 10:43:23	Distance (km) 4.067 44.940 10.530 101.100	Effective Time 0:31:12 3:47:03 4:44:05	0:18:37 2:04:33 0:31:47	0:12:35 1:42:30 4:12:18	OPERATIC Operating Operating DISTANCE Trip Distan FUEL TAN Initial volum Maximum Fueling vol Fuel drain: FUEL TAN Initial volum	Period (Calendar Da Days (Working Days E ace: 0.447 km <u>IK 1</u> me: 0.0 litres ne: 0.0 litres volume: 0.0 litres volume: 0.0 litres <u>volume: 0.0 litres</u> <u>volume: 0.0 litres</u> <u>volume: 1.0 litres</u>	iys): 1	El In Fi M Fi Tu In	UEL TANK 3 iitial volume: (inainal volume: (inainal volume: (aximum volu ueling volume) uel drain: 0.0 DTAL FUEL iitial volume:	0.0 litres 0.0 litres e: 0.0 litres me: 0.0 litres litres litres 0.0 litres		
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vehicle and fuel monitoring

Operating Day Distance: 599. Summary Wor	od (Calendar Days) s per Period: 21 308 km king Time (hh:mm:s ctive Time (hh:mm:	ss): 80:00:57					
Date	Work Starting	Work Finishing	Work Time	Distance (km)	Effective Time	Driving Time	Stand Time
12/01/2010	12/01/2010 9:02:07	12/01/2010 11:39:32	2:37:25	4.067	0:31:12	0:18:37	0:12:35
13/01/2010	13/01/2010 5:37:56	13/01/2010 17:35:30	11:57:34	44.940	3:47:03	2:04:33	1:42:30
14/01/2010	14/01/2010 4:53:58	14/01/2010 15:37:21	10:43:23	10.530	4:44:05	0:31:47	4:12:18
15/01/2010	15/01/2010 5:47:30	15/01/2010 9:31:22	3:43:52	101.100	2:16:25	1:39:46	0:36:39
16/01/2010	16/01/2010 4:59:37	16/01/2010 16:50:06	11:50:29	120.000	3:59:40	2:31:43	1:27:57
17/01/2010	17/01/2010 4:32:50	17/01/2010 17:33:44	13:0:54	68.300	3:54:10	2:13:28	1:40:42
18/01/2010	18/01/2010 4:26:43	18/01/2010 16:06:59	11:40:16	92.710	6:01:54	4:14:13	1:47:41
19/01/2010	19/01/2010 4:50:45	19/01/2010 16:33:09	11:42:24	118.300	4:50:38	3:24:59	1:25:39
20/01/2010	20/01/2010 5:15:19	20/01/2010 7:59:59	2:44:40	39.370	2:07:04	1:08:36	0:58:28

Detailed Idle Time (Parking)

Total Quantity of Parking: 8

Total Idle time (Parking Time) : 02:35:59

Idle Time Begining	Idle Time Ending	Idle Time Duration	Latitude	Longitude
05:07:00	05:16:34	00:09:34	25.245501	51.4683
05:17:02	05:50:41	00:33:39	25.245501	51.4683
08:53:58	09:08:28	00:14:30	25.245501	51.4683
09:11:37	09:47:10	00:35:33	25.242701	51.472801
09:52:55	10:08:23	00:15:28	25.242701	51.472801
10:10:44	10:19:30	00:08:46	25.245399	51.4683
10:41:58	11:12:46	00:30:48	25.2428	51.4729

TimePeriod:	01-09-2014 00:00	- 01-10-2014 00	:00									
-		-								0		-
Dr	iver	Work Time hour:min	Overspeed Driving %	Milleage km	Spe Max km/h	Avg km/h	Max /	vg per	unt Ma 100 m/		count	Tota Poin
Ken Kenny		46:29	6	2880.2	116.0	71.3	2.15 0		69 2	0 0.2		30.1
Ron1 Ron1		23:53	0	967.5	104.5	52.9	1.85 0	.30 2	07 2.	0.3	5 13.02	24.5
Brunei 4 FES		2:33	0	93.3	95.5	40.5	1.65 0	20 1.	07 2.	0 0.2	5 7.50	17.4
RON 2 FES		0:00	0	0.0	0.0	0.0	0.00 0	.00 0.	00 0.	0.0	0.00	0.0
Ivanov Alexey		0:00	0	0.0	0.0	0.0	0.00 0	.00 0	00 0.	0.0	0.00	0.0
RON RON		0:00	0	0.0	0.0	0.0	0.00 0	.00 0.	00 0.	0.0	0.00	0.0
		Vehicle	e Eco-[Drivin	g anc	l Safe	ty Driv	/ing				
Report TimePeriod:	01 Sep 2014 00:00			Drivin	g anc	l Safe	ty Driv	/ing				
Report TimePeriod: Report Created:	01 Sep 2014 00:00 16 Oct 2014 15:51			Driving	g anc	l Safe	ty Driv	/ing				
				Drivin	g and	I Safe	ty Driv	/ing				
Report Created:	16 Oct 2014 15:51 311			Driving	g anc	I Safe	ty Driv	/ing				back to
Report Created: Total Trips:	16 Oct 2014 15:51 311 2014		23:59					/ing	Acceli	ation m/s*	Decelera	0.000.000
Report Created: Total Trips:	16 Oct 2014 15:51 311				g and Durations	I Safe			Acceli Maximur		Decelera	tion m/s
Report Created: Total Trips:	16 Oct 2014 15:51 311 2014		23:59	(1	-		Spee	d km/h			Decelera	tion m/s Avera
Report Created: Total Trips:	16 Oct 2014 15:51 311 2014	– 30 Sep 2014 2	23:59 Time	6.19:17	Durations	Distance	Spee Maximum	d km/h Average	Maximur	Average	Decelera Maximum	tion m/s Avera 0.3
Report Created: Total Trips:	16 Oct 2014 15:51 311 2014	– 30 Sep 2014 2	23:59 Time 08:09:49 - 0	18:19:17 18:43:23	Durations 00:09:28	Distance 3.51	Spee Maximum 6200	d km/h Average 0.51	Maximur 1.15	Average 0.27	Decelera Maximum 1.55	tion m/s Avera 0.3 0.2
Report Created: Total Trips:	16 Oct 2014 15:51 311 2014	– 30 Sep 2014 2	23:59 Time 08:09:49 - 0 08:40:54 - 0	18:19:17 18:43:23 0:13:11	Durations 00:09:28 00:02:29	Distance 3.51 0.60	Spee Maximum 62.00 46.50	d km/h Average 0.51 0.53	Maximur 1.15 1.50	0.27 0.39	Decelera Maximum 1.55 1.20	tion m/s Avera 0.3 0.2 0.3
Report Created: Total Trips:	16 Oct 2014 15:51 311 2014	– 30 Sep 2014 2	23:59 Time 08:09:49 - 0 08:40:54 - 0 10:11:37 - 1	18:19:17 18:43:23 0:13:11 1:03:35	Durations 00:09:28 00:02:29 00:01:34	Distance 3.51 0.60 0.10	Spee Maximum 6200 46:50 24:00	d km/h Average 0.51 0.53 0.64	Maximur 1.15 1.50 0.40	Average 0.27 0.39 0.38	Decelera Maximum 1.55 1.20 0.45	tion m/s Averag 0.3 0.2 0.3 0.4
Report Created: Total Trips:	16 Oct 2014 15:51 311 2014	– 30 Sep 2014 2	23:59 Time 08:09:49 - 0 08:40:54 - 0 10:11:37 - 1 10:33:39 - 1	18:19:17 18:43:23 0:13:11 1:03:35 5:10:45	Durations 00:09:28 00:02:29 00:01:34 00:29:56	Distance 3.51 0.60 0.10 1.25	Spee Maximum 62.00 46.50 24.00 39.50	d km/h Average 0.51 0.53 0.64 0.62	Maximur 1.15 1.50 0.40 0.90	Average 0.27 0.39 0.38 0.31	Decelera Maximum 1.55 1.20 0.45 1.40	back to 1 tion m/s Averag 0.3 0.2 0.3 0.4 0.2 0.5

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	2014 00:00 - 30 ce	H 2014 23:59					••••••
	2014 23:34			••••••			
***************************************	•••••						
Toyota Hilux					1011		back to t
Driver		Date	Durations	Spe Treshhold M	eed km/h		Location
	Kenny Ken	Вт, 16 сен 2014, 16:42:26	00:01:00	Tresnoid M	110	109	4,967330, 114.86470
	Kenny Ken	Вт. 16 сен 2014, 16:45:11	00:00:40	10	110	110	4.983040; 114.90266
	Kenny Ken	Вт, 16 сен 2014, 16:51:16	00:00:35	2	102	102	4.990260; 114.97007
	Kenny Ken	Вт, 16 сен 2014, 16:53:41	00:00:40	2	102	102	5.008890; 114.99996
	Kenny Ken	Вт, 16 сен 2014, 16:54:56	00:00:40	4	104	103	5.024330; 115.01092
	Kenny Ken	Ср, 17 сен 2014, 00:58:34	00:00:40	14	114	114	4.988310; 114.92085
	Kenny Ken	Ср, 17 сен 2014, 16:57:08	00:00:40	6	106	106	4.580330; 114.24432
	A descent of the set	A	ALC: N. A. A. A. A.		107		4,832380; 114,75164
C-1 27	Kenny Ken Kenny Ken	Ср, 17 сен 2014, 17:52:48 Ср, 17 сен 2014, 17:53:58 eleration/Dec	00:00:45 00:00:55	on Vio	102	107 102 Overview	
Total Violations:	Kenny Ken	Ср, 17 сен 2014, 17:53:58	00:00:55	2	102	102	
	Kenny Ken Fleet: Acc	Ср, 17 сен 2014, 17:53:58	00:00:55	2	102	102	<u>4.836200; 114.7686</u> ;
Total Violations:	Kenny Ken Fleet: Acc 465	Ср, 17 сен 2014, 17:53:58	eleratio	on Vio	102	¹⁰² Overview	<u>4.836200; 114.76861</u>
Total Violations: Toyota Hilux	Kenny Ken Fleet: Acc 465	ср, 17 сен 2014, 17:53:58 eleration/Dec Dat	oo:oo:55 eleratio	on Viol	102 lation (celeration	102 Overview Deceleration	<u>4.836200; 114.76861</u> back to top Location
Total Violations: Toyota Hilux	Kenny Ken Fleet: Acc 465	ср, 17 сен 2014, 17:53:58 eleration/Dec Dat	00:00:55 eleratio	2 on Vio Acc 5:39	102 lation (celeration	Deceleration m/s ²	<u>4.836200; 114.76861</u> <u>back to top</u> Location <u>4.577730; 114.204803</u>
Total Violations: Toyota Hilux	Kenny Ken Fleet: Acc 465	ср, 17 сен 2014, 17:53:58 eleration/Dec Dat 01 Вс, 31 авг 21	00:00:55 eleratio te 014, 16:16 014, 22:12	2 on Vio Acc 5:39 2:08	102 lation (celeration m/s ²	Deceleration m/s ²	<u>4.836200; 114.76861</u> back to top
Total Violations: Toyota Hilux	Kenny Ken Fleet: Acc 465	ср, 17 сен 2014, 17:53:58 eleration/Dec Dat 01 Вс, 31 авг 21 Вс, 31 авг 21	00:00:55 eleratio 014, 16:16 014, 22:12 014, 22:36	2 on Vio Acc 5:39 2:08 5:03	102 lation (celeration m/s ²	102 Overview Deceleration m/s ² 1.55	<u>4.836200; 114.76861</u> <u>back to top</u> <u>Location</u> <u>4.577730; 114.204803</u> <u>4.571930; 114.202667</u>
Total Violations: Toyota Hilux	Kenny Ken Fleet: Acc 465	ср, 17 сен 2014, 17:53:58 eleration/Dec Dat 01 Вс, 31 авг 21 Вс, 31 авг 21 Вс, 31 авг 21 Вс, 31 авг 21	00:00:55 eleratio 014, 16:16 014, 22:12 014, 22:36 014, 22:43	2 on Vio Acc 3:39 2:08 3:03 3:13	102 lation (celeration m/s ²	102 Dverview Deceleration m/s ² 1.55 1.70	<u>4.836200; 114.76861</u> <u>back to top</u> <u>Location</u> <u>4.577730; 114.204803</u> <u>4.571930; 114.202667</u> <u>4.597680; 114.276459</u>

	Trip Overview
Report TimePeriod:	01 Sep 2014 00:00 - 30 Sep 2014 23:59
Report Created:	16 Oct 2014 15:51
Total Trips:	311

Mon, 01 Sep 2014

-	Time	Durations	Distance	Speed	km/h	Acceliration m/s*		Deceleration m/s*	
Driver	lime	Durations	Distance	Maximum	Average	Maximum	Average	Maximum	Average
Ron1 Ron1	08:09:49 - 08:19:17	00:09:28	3.51	62.00	0.51	1.15	0.27	1.55	0.35
	08:40:54 - 08:43:23	00:02:29	0.60	46.50	0.53	1.50	0.39	1.20	0.28
	10:11:37 - 10:13:11	00:01:34	0.10	24.00	0.64	0.40	0.38	0.45	0.33
	10:33:39 - 11:03:35	00:29:56	1.25	39.50	0.62	0.90	0.31	1.40	0.48
	14:10:33 - 15:10:45	01:00:12	31.97	99.50	0.57	1.55	0.31	1.90	0.27
Ron1 Ron1	17:14:10 - 17:32:36	00:18:26	2.83	58.50	1.67	1.30	0.43	2.10	0.56
Total Trips: 6		02:02:05	40.28	99.50	0.75	1.55	0.35	2.10	0.38

Vehicle Utilization Report							
Vehicle Name:	Toyota Hilux	Model:					
Plate Number:	BAM6076	Group:	1				
Time Period:	17 сен 2014 00:00 - 1	7 сен 2014 23:59					

Operating Period (Calendar Days): 0 Operating Days per Period: 1 Distance: 231.092 km Summary Working Time (hh:mm:ss): 23:59:54 Summary Effective Time (hh:mm:ss): 4:13:03

Date	Work Start - Work Finish	Work Time	Work Time %	Distance (km)	Effective Time	Effectivity %	Driving Time	Stand Time	Parking (pcs)
17-09-2014	0:00:00 - 23:59:54	23:59:54	1E2	231.09	4:13:03	18	3:58:03	0:15:00	16

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About Monitoring Software and Monitoring Service Road Tanker: Fuel Compartments Unloading



GuardMagic vehicle and fuel monitoring



GuardMagic Office PC based Monitoring. (Complete Solution)

About VehicleStation, FleetStation Monitoring Software

Vehicle Station and FleetStation are the series of a special program intended for "Real Time" mobiles and stationary objects monitoring (All-In-One monitoring software).

VehicleStation (FleetStation) give you secure access to all your vehicle in any part of the world. Monitoring software located in your office server (office PC) and all information about your vehicle located only in your office.



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About VehicleStation, FleetStation Monitoring Software



VehicleStation - Administrator 28-08-2014

Settings Help Language

Monitor: Vehicle, Driver, Trailer

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About VehicleStation, FleetStation Monitoring Software





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WEB Based Monitoring. (PowerTrace Monitoring Service)

About PowerTrace Monitoring Service

WEB based PowerTrace monitoring service give you 24-hour secure access to all your vehicle from any PC in any part of the world.

WEB based system does NOT require any software installation or any your support of system operation. The only requisite is a computer with internet access.

Powerful PowerTrace web based vehicle monitoring service give the following:

- Online tracking of your vehicles 24/7/365;
- Overview of trips, parking and stop times;
- Geofencing institution;
- Online Fuel monitoring;
- Generation different reports and graphs;
- Automatic reporting;

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vehicle and fuel monitoring

- Alerts and warning sending;
- Data storage up to 15 months;
- Information downloaded in XML, CSV for management information;

-Online monitoring via Smartphone.





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